

PRB. 15.12.

$$\begin{array}{c} E \\ \pi \downarrow \\ M \end{array} \quad p \in M \quad E_p \supset E'_p \text{ subspace}$$

$$E' := \bigcup_{p \in M} E'_p, \quad \pi' : E' \rightarrow M, \quad \pi' = \pi|_{E'}, \quad \text{THEN } E' \text{ is a subbundle of RANK } \ell \Leftrightarrow \forall p \in M \exists U \ni p \text{ and } \sigma_1 : U \rightarrow E$$

smooth sect. $\sigma_i : U \rightarrow E$ of E over U .

such that for $\forall q \in U : \{\sigma_1(q), \dots, \sigma_\ell(q)\}$ is a base of E'_q . (In particular, they are contained in E'_q).

$\Rightarrow$ It is evident: consider a v.bundle chart

$$\begin{array}{ccc} \Phi : E'|_U & \xrightarrow{\cong} & U \times \mathbb{K}^\ell \\ \downarrow & \swarrow & \downarrow \\ U & & U \end{array} \quad \sigma_i(q) = \Phi^{-1}(q, e_i). \quad (\text{a frame field over } U).$$

$\Leftarrow$ Define trivializations:

$$\Phi' : E'|_U \cong U \times \mathbb{K}^\ell$$

$$\Phi'(e'_p) = (p, \lambda^1, \dots, \lambda^\ell), \text{ where } e'_p = \lambda^i \sigma_i(p).$$

The transition maps will be formed by change of base matrices, smoothly dependent on p .

PRB 15.20. $t \in [0, b]$, $\begin{array}{c} E \\ \pi \downarrow \\ [0, b] \end{array}$ with connection $\mathcal{H}$.

$\frac{\partial}{\partial t}$ is a vector field on $[0, b]$, and $\tilde{\partial}$ is its horiz. lift

1). $\gamma : [0, a] \rightarrow E$ of $\tilde{\partial} \Rightarrow \pi \circ \gamma$ is an integral curve of $\frac{\partial}{\partial t}$. (Indeed, $\dot{\gamma}_t = \tilde{\partial}_{\gamma(t)}$)

$$(\pi \circ \gamma)'_t = (d\pi)_{\gamma(t)} \dot{\gamma}_t = (d\pi)_{\gamma(t)} \tilde{\partial}_{\gamma(t)} = \frac{\partial}{\partial t} \Big|_{\pi \gamma(t)}$$

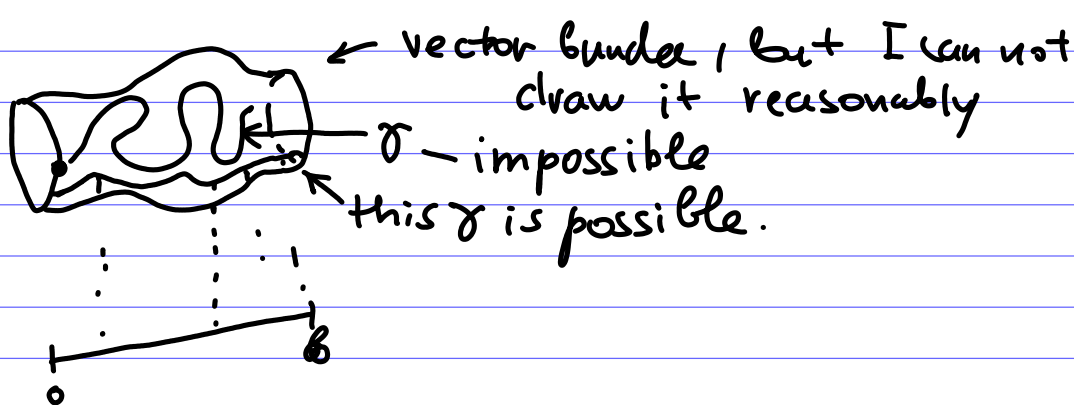
But the integral curve of $\frac{\partial}{\partial t}$ is $t \mapsto t + \text{const.}$

$$\text{So } \pi \gamma(t) = t + \text{const}$$

but $\pi \gamma(0) = 0 \Leftrightarrow \gamma(0) \in E_0$, so $\text{const} = 0$

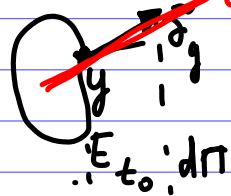
$$\pi \gamma(t) = t$$

$$(1) \quad \varphi(t) \text{ s.t. } \frac{\partial \varphi}{\partial t} = \frac{d\varphi}{dt} = 1$$



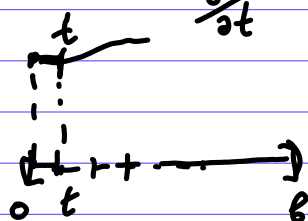
2). $\forall t_0 < b \exists \varepsilon = \varepsilon(t_0) > 0$ s.t. all integral curves of $\tilde{\gamma}$ originating at a point in E_{t_0} are defined at least on $[t_0, \varepsilon)$.

Hy is one-dimensional.
int curve is a solution of SODE
a Cauchy problem.
 $\exists$ a unique sol. locally.

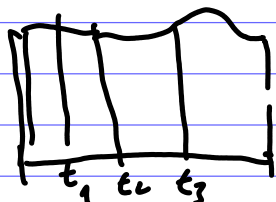


for $(-\frac{\partial}{\partial t})$ this is the same.

3).



$t \rightarrow \varepsilon(t), [t, \varepsilon(t))$
 $\{ [0, \varepsilon(0)), (t, \varepsilon(t)) \text{ for } t > 0 \}$
an open covering of $[0, b]$
 $\rightarrow$ find a finite covering.



$\cup t_0, t_1, \dots, t_s.$

$\otimes$ (see an addition below)

PROB. 15.24.

E
 $\pi \downarrow$
 M

TE
 $d\pi \downarrow$
 TM

— a smooth map

A fiber bundle (do not say a vector bundle):

indeed, locally: $\Phi_U: E|_U \cong U \times V$

$TE|_U \cong TU \times TV \cong TU \times V$

$(d\pi)^{-1}(TU) = \{ v \in TE \mid \text{open neigh. in } TM, d\pi(v) \in TU \}$

$v \in T_y E \Rightarrow d\pi(v) \in T_{\pi(y)} M$

this means that $(d\pi)^{-1}(TU) = TE|_U$

In fact, if U is trivializing both for E and TM

Then:

$$TE|_U \cong TU \times V \xrightarrow{\sim} U \times W \times V \xrightarrow{\sim} TE|_M$$

$\cong$
 $U \times W \times V$

TE
 $\downarrow$
 E

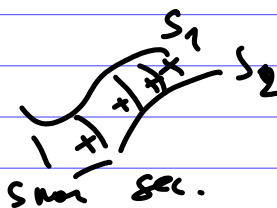
TE
 $\downarrow$
 TM

TE
 $\downarrow$
 M

Now about the structure of a vector bundle on M .
 To introduce it there are 2 ways:

1) Define linear structure on images of triv. maps for f.b. structure and verify that the corresponding transition maps will be fiber-wise linear.

2) To define operations globally as smooth op. (indep. of charts in each fiber)


 $\rightarrow s_1 + s_2$ is also smooth.

$$u \oplus v := (d\alpha)(u, v) \rightarrow \{u, v \in TE \mid \text{with } (d\pi)u = (d\pi)v\}$$

where $\alpha(y_1, y_2) := y_1 + y_2$ for $(x, y_i) \in E + E$

$TE \ni u, v \xrightarrow{u \oplus v} \text{only if they are in the same fiber}$
 $\downarrow d\pi$
 TM

$\leftarrow$ for i.e. $(d\pi)u = (d\pi)v$

$$d: E \oplus E \rightarrow E$$

$$(d\alpha): T(E \oplus E) \rightarrow TE$$

$$\{ (v, w) \in TE \times TE \mid (d\pi)v = (d\pi)w \}$$

$$c \odot v$$

evid. smooth. So (to perform way No 2) we need to verify the axioms (8 axiom.) of a linear space.

For α : Distributive law:

$$\begin{aligned} \alpha \odot (v \boxplus w) &= d\mu_\alpha \cdot (d\alpha)(v, w) = \\ &= d(\mu_\alpha \circ \alpha)(v, w) \quad \leftarrow \text{Easier to use the 3d def.: } v = [\gamma(t)] \\ &= [a \cdot (\gamma(t) + w(t))] = [a \cdot \gamma(t)] + [a \cdot w(t)] = \\ &= (\alpha \odot v) \boxplus (\alpha \odot w). \end{aligned}$$

On Friday at 14:00.

⊗ addition to Prob. 15.20.

while finding the curve "by stages" in 3), we do not know at which point of E_t we arrive. Thus we need an estimation (finding ε) in 2) simultaneously for all points e in E_{t_0} .
"starting"

To obtain such $\varepsilon = \varepsilon(t_0)$ we first consider some inner product in E_{t_0} and the corresponding sphere $S = \{e \in E_{t_0} \mid |e| = \langle e, e \rangle^{1/2} = 1\}$. As above in 2) we find ε_e for each $e \in S$. By the same argument (from ODE) this ε_e (maximal) depends smoothly on the initial data (in particular, e). So this continuous (sufficient) function $e \mapsto \varepsilon_e$ has minimum $0 < \varepsilon = \min_{e \in S} \varepsilon_e$, because S is a compact set.

Now we wish to prove that this ε is valid for all E , not only for $S \subset E$. If $e \in E$ is an arbitrary element, then $e = a \cdot e_1$, where $e_1 \in S$ (for $|e| \neq 0$ one can take $e_1 = \frac{e}{|e|}$, $a = |e|$). We claim that $a\gamma(t)$ will be the integral curve of $\tilde{\partial}$, starting in $a e$, if γ was the integral curve of $\tilde{\partial}$ starting in $e \in E_{t_0}$ (and of course $a\gamma(t)$ is defined for $[t_0, t_0 + \varepsilon)$ too). Indeed, if $\tilde{\partial}|_{t_0} \in \mathcal{H}_e$, then $(a\gamma)'|_{t_0} = (d\mu_a)\tilde{\partial}|_{t_0} \in \mathcal{H}_{ae}$ by the property 2) of the definition of an Ehresmann connection.